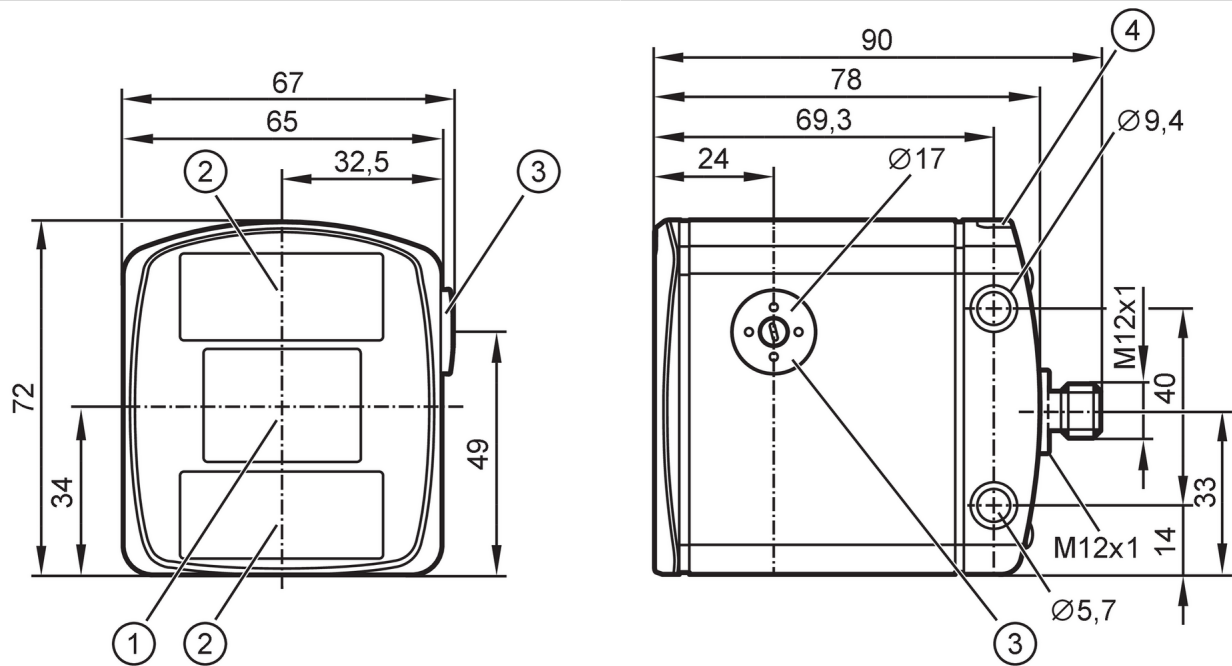


O3D310



3D sensor

O3DIRDKG/E1/GM/T/40



- 1 lens
- 2 Illumination unit
- 3 Focus adjustment screw
- 4 LED 2-color yellow/green



Product characteristics

Type of light	Infrared light
Image resolution 3D [px]	176 x 132
Angle of aperture 3D [°]	40 x 30; (nominal value without lens distortion correction)
Image repetition frequency 3D [Hz]	25
Housing	rectangular

Application

Application	Dimensioning of the object; Completeness monitoring; Level monitoring; distance monitoring; volume monitoring; robot gripper navigation; depalletizing
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Electrical data

Operating voltage [V]	20.4...28.8 DC; (EN 61131-2)
Current consumption [mA]	420; (maximum mean value: < 1600 mA)
Max. current consumption [mA]	2400; (peak current pulsed)
Power consumption [W]	10; (typical value)
Protection class	III
Overvoltage category	II
Type of light	Infrared light
Image sensor	PMD 3D ToF-Chip
Integrated lighting	yes; (infrared: 850 nm invisible radiation LED)

Inputs / outputs

Number of inputs and outputs	Number of digital inputs: 2; Number of digital outputs: 3; Number of analog outputs: 1
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O3D310



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Inputs	
Trigger	24 V PNP/NPN (IEC 61131-2 Typ 3)
Number of digital inputs	2
Input circuit of digital inputs	24 V PNP/NPN; (configurable; IEC 61131-2 Typ 3)
Outputs	
Total number of outputs	3
Number of digital outputs	3; (configurable)
Output function	24 V PNP/NPN; (EN 61131-2)
Max. voltage drop switching output DC [V]	1
Max. current load per output [mA]	100
Number of analog outputs	1; (configurable)
Analog current output [mA]	4...20
Max. load [Ω]	500
Analog voltage output [V]	0...10
Min. load resistance [Ω]	10000
Precision analog output [%]	1
Short-circuit protection	yes
Type of short-circuit protection	yes (non-latching)
Overload protection	yes
Resolution of analog output	12 bit
Monitoring range	
Operating distance [mm]	300...8000
Note on operating distance	object size: 200 x 200 mm
	reflectivity: 18 %
Image resolution 3D [px]	176 x 132
Angle of aperture 3D [°]	40 x 30; (nominal value without lens distortion correction)
Image repetition frequency 3D [Hz]	25
Measuring/setting range	
Measuring range [m]	< 30
Software / programming	
Parameter setting options	via PC with ifm Vision Assistant
Interfaces	
Communication interface	Ethernet
Ethernet	
Transmission standard	10Base-T; 100Base-TX
Transmission rate	10; 100
Protocol	TCP/IP; EtherNet/IP; PROFINET
Factory settings	IP address: 192.168.0.69
	subnet mask: 255.255.255.0
	gateway IP address: 192.168.0.201

O3D310



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Ethernet - EtherNet/IP		
Usage type	Data transmission	
Ethernet - PROFINET		
Usage type	Data transmission	
Ethernet - TCP/IP		
Usage type	Parameter setting; Data transmission	
Operating conditions		
Ambient temperature	[°C]	-10...50
Storage temperature	[°C]	-40...85
Protection	IP 65; IP 67; IP 69K	
Max. immunity to extraneous light	[klx]	8; (with reduced measuring accuracy and repeatability: < 100)
Tests / approvals		
EMC	DIN EN 61000-6-4	radiation of interference / industrial environments
	DIN EN 61000-6-2	noise immunity / industrial environments
Shock resistance	DIN EN 60068-2-27	50 g / (11 ms) not repetitive
	DIN EN 60068-2-27	40 g / (6 ms) repetitive
Vibration resistance	DIN EN 60068-2-6	2 g / (10...150 Hz)
	DIN EN 60068-2-64	2.3 g RMS / (10...500 Hz)
Photobiological safety	exempt group; (DIN EN 62471)	
Electrical safety	DIN EN 61010-2-201	electrical supply only via PELV circuits
MTTF	[years]	43.08
Mechanical data		
Weight	[g]	1217.5
Housing	rectangular	
Dimensions	[mm]	72 x 67 x 90
Material	housing: stainless steel (1.4404 / 316L); front lens: PMMA; Function display: PA	
Tightening torque	[Nm]	< 0.8
Displays / operating elements		
Display	Function	2 x LED, green Ethernet Power
	Switching status	2 x LED, yellow OUT 1 OUT 2
Accessories		
Items supplied	Protective covers	
Remarks		
Pack quantity	1 pcs.	
Electrical connection - Ethernet		
Connector: 1 x M12; coding: D; Contacts: 4		
		
1	TD +	
2	RD +	
3	TD -	
4	RD -	

O3D310

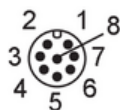


3D sensor

O3DIRDKG/E1/GM/T/40

Electrical connection - Process connection

Connector: 1 x M12; coding: A; Contacts: 8



1	U+
2	trigger input
3	GND
4	Switching output 1 digital or analog
5	Switching output 3 digital Ready
6	Switching output 2 digital
7	Switching input 1 digital
8	Switching input 2 digital

Other data

Field of view size with lens distortion correction

Measuring range / distance [m]	Length [m]	Width [m]
0.50	0.26	0.35
1.00	0.52	0.69
2.00	1.04	1.39
3.00	1.56	2.08
4.00	2.08	2.78
5.00	2.61	3.47

Accuracy of dimensioning of the object

Measuring range / distance [m]	accuracy object size (Length, Width, Height) [mm]	accuracy object position (X, Y, Z coordinates) [mm]	accuracy angle of rotation [°]
typical value	typical value	typical value	typical value
1.0...3.0	± 10	± 5	± 1

Operating distance:	0.3 ... 5 m
Image repetition frequency:	1 Hz
information applies for:	
rectangular objects	
reflectivity:	6...90 % for non-glossy objects
minimum object size:	100x100x100 mm
object in centre of the image	
object speed:	< 0.2 m/s



3D sensor

O3DIRDKG/E1/GM/T/40

Completeness monitoring

	object speed < 0.2 m/s [mm]	object speed > 0.2 m/s [mm]
typical value:		
minimum height	25	45
Image repetition frequency [Hz]	5	
Operating distance [m]	0.3...5	
max. packaging size (orthogonal packaging arrangement)	maximum number of objects 64	
The image repetition frequency is reduced by using the position tracking function		

level and distance monitoring

Measuring range / distance [m]	repeatability of the measured distance values on grey objects (18% reflectivity) [mm]	repeatability of ROI of 50x50 pixels on grey objects [mm]	Accuracy (reflectivity 6-90%) [mm]
	typical value	typical value	typical value
0.3...1.0	8	0.3	± 7
1.0...3.0	12	0.4	± 7
3.0...5.0	20	0.7	± 10
5.0...7.0	30	1.0	± 15
7.0...8.0	50	1.7	± 20
measured in the center of the image at an ambient temperature of 20°C			
Repeatability		1 σ	
The repeatability can be optimized with filter functions			
Temperature drift -10...+50 °C		0.2 mm/K	

robot gripper navigation and depalletizing

	robot gripper navigation	depalletizing
Operating distance [m]	0.2...6	0.5...6
object types	any object shape	closed rectangular objects
minimum object size [mm]	20 x 20 x 20	50 x 50 x 50 at minimum operating distance
accuracy object position [mm]		
typical value:	± 10 rectangular objects	± 15
accuracy angle of rotation [°]		
typical value:	± 1 rectangular objects	± 3
object speed [m/s]	< 0.2	
Image repetition frequency [Hz]	2 for one object to be measured	1
maximum number of objects	20	